

# *General announcements*

## *The Island Series:*

You have been kidnapped by a crazed physics nerd and left on an island with twenty-four hours to solve the following problem. Solve the problem and you get to leave. Don't solve the problem and you don't.

*The problem:* You are told that a mass will be accelerated, and the question will be, “Will the *velocity change* be relatively big or relatively small.” You respond with a, “What the hell, how should I know,” at which time your captor says, “Oh, yeah, OK, well, I'll let you ask two questions before giving your answer, but not “is the velocity change big or small” . . . and know that I (the captor) had a bad experience with kinematics when young and any allusion to that approach will outrage me.”

What two questions should you ask?

# *Solution to Island Problem*

*What* does *govern* how much *velocity change* a body experiences under the influence of a force? The two parameters that will matter are:

*The magnitude of the force* (the bigger the force, the larger the velocity change will likely be); and

*The distance over which the force acts* (the farther the force acts, the more the body will pick up speed);

*Except* there is a problem with this as stated. We will take a look at what it is shortly.

# CHAPTER 7:

## Work and Energy

*To date*, you have seen two approaches to problem-solving in this class:

1.) *Kinematics says*: that if a body's acceleration is constant, look to see what information you are given, look to see what you are trying to determine, then find a **kinematic equation** that has everything you know along with what you are trying to determine. I call it *idiot physics* because you can be an idiot and do just fine with it. All it really is is pattern recognition.

2.) *Newton's Laws say*: if a body experiences a **net force along some line**, that force will be **proportional to the acceleration** of the body along that line with the **proportionality constant being the body's mass**. It is a considerably more powerful approach than kinematics as considerably less information is required to make it work.

*We are now* ready to look at the world from a completely different perspective, one in which a system's **energy content** is the key. It will begin with a definition, that of *work*, from which all else will follow. First, though, some non-AP related exotica

# What is Energy?

(this is not an AP-related topic)

*You are* out in space and you give a 1.00000 kg object a push with a constant force. What changes?

*The acceleration* won't change as the force is constant, but the velocity will; time will; momentum will; position will.

*There is* one other things that will change in this case, though not by any amount that you will notice. The body's mass will change (remember, mass is a relative measure of a body's inertia).

*In fact*, a velocity/mass breakdown for your 1.0000 kg mass object is found on the next slide;

## velocity

## mass

zero

1.00000000000000000000000000000000 kg

100 mi/sec

10,000 mi/sec

100,000 mi/sec

170,000 mi/sec

180,000 mi/sec

185,000 mi/sec

185,900 mi/sec

185,999 mi/sec

185,999.9999 mi/sec

186,000 mi/sec

*Apparently*, putting energy *into* a system at low velocities shows itself by changing the body's *energy of motion* (it's *kinetic energy*) whereas putting energy into a system at velocities close to the speed of light *changes the body's mass*.

*You are* are familiar with the key to this rather bizarre behavior. What was the first relativistic equation you have ever learned from Einstein?

$$E = mc^2$$

*It says* claims is that **mass** and **energy** are **different forms of the same thing**.

*Don't believe me?* Take **1.000 grams of hydrogen** and **fuse it**. You will end up with **.993 grams of helium**. Where did the **missing .007 grams** go? *Turned into pure energy*, enough energy to send *three-hundred and fifty*, 4000 pound **Cadillacs** (the old school kind) **100 miles into the atmosphere**. The sun fuses 657,000,000 TONS of hydrogen into approximately 653,000,000 tons of helium *every second*. That's how it generates enough energy to heat our planet 93,000,000 miles away.

*When Feynman* (Nobel laureate from Caltech) was asked by me at a CAIS meeting what energy was, he said, simply, "I have no idea." And in saying that, he spoke for the physicists of the world! We know how to *use energy*, how to *store it*, how to *generate it*, how to *transfer it great distances*, but we have absolutely no idea *what it is*.

*Fortunately*, you don't need to know *what it is* to use the idea as a problem-solving tool, which is exactly what we are about to do in a non-relativistic setting.

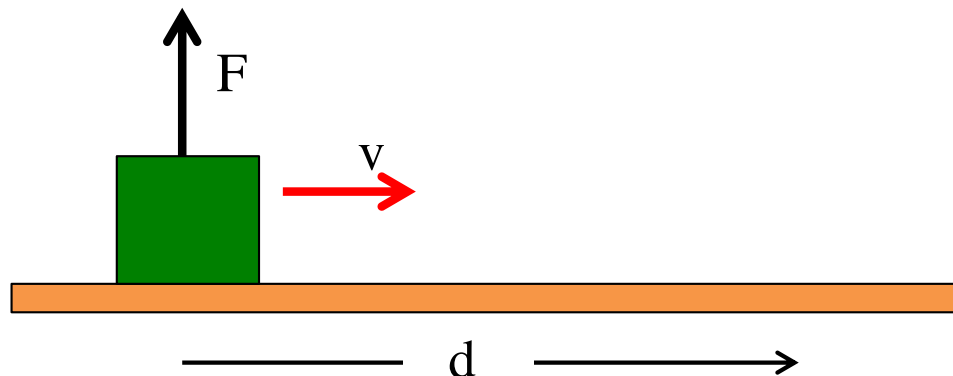
# Work

*So what does govern* the *velocity change* a body experiences under the influence of a force at low velocities? The two parameters that will matter are:

*The magnitude of the force* (the bigger the force, the larger the velocity change will likely be); and

*The distance over which the force acts* (the farther the force acts, the more the body will pick up speed);

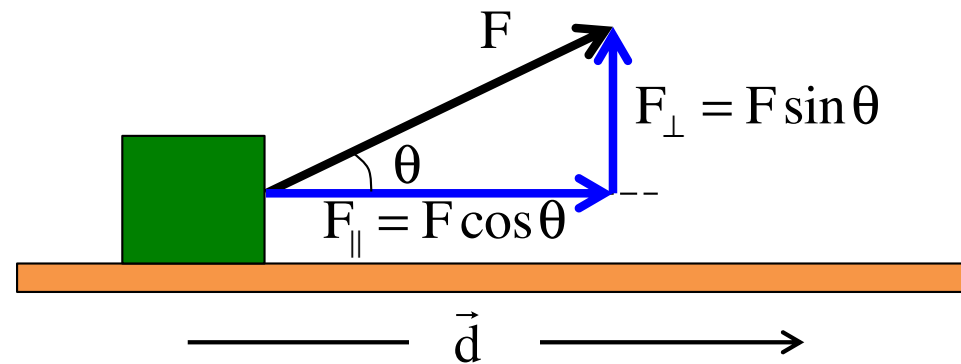
*There is a problem* with this as stated, though. Consider the following force and displacement . . . will  $F$  be changing that body's velocity as it moves across the table?



*NO!!! This force* will generate *NO VELOCITY CHANGE* . . . yet there's a force and displacement involved . . . so what's the deal?



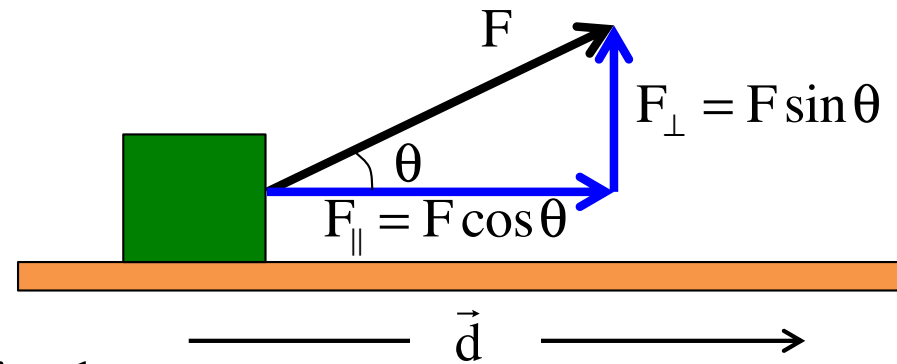
*To understand* the problem, we need to look at a little more general situation. Consider a constant force oriented at an angle  $\theta$  with the displacement vector. In that case, we have:



*Clearly*, the **perpendicular component** of the force  $F_{\perp}$  *will do nothing to change the body's velocity* (assuming it doesn't yank the block off the tabletop), whereas the **parallel component**  $F_{\parallel}$  *WILL effect a velocity change*.

*In fact*, the product of  $F_{\parallel}$  and the **magnitude of  $\vec{d}$**  will yield a number that, **if large**, would suggest a relatively large velocity change, and **if small**, a would suggest a relatively small velocity change.

*This product*, the product of the, *magnitude of the component-of-the-force-along-the-line-of-the-displacement* and *the magnitude-of-the-displacement* is important enough to be given a special name. It is called **WORK**. Formally, it is defined as:



$$W = F_{\parallel}d$$

*Note that* the units are *newton-meters*, or joules (the units of energy):

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*Looking at* the geometry in the sketch, this is also written as:

$$W = (F \cos \theta)d$$

*where*  $\theta$  is the angle between *the line of the force* and *the line of the displacement* and  $d$  is the *magnitude of the displacement*.

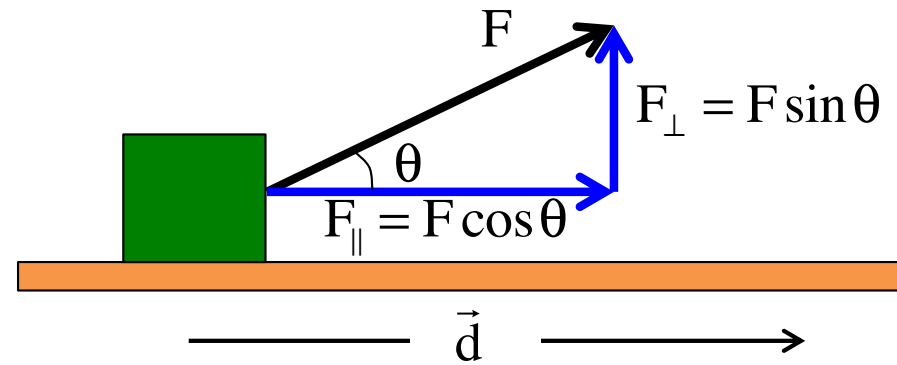
*It is also* not uncommon to see this quantity written as:  $W = |\vec{F}| |\vec{d}| \cos \theta$

*Or* the *magnitude of one vector* times the *magnitude of the second vector* times the *cosine of the angle between the line of the two vectors*:

*Because* this kind of operation is used so often in physics (that is, multiplying the *magnitude of one vector* times the *component of the second vector along the line of the first*), the operation is given a special name and designation. It is called a **DOT PRODUCT**, and its use allows us to write out the work relationship as:

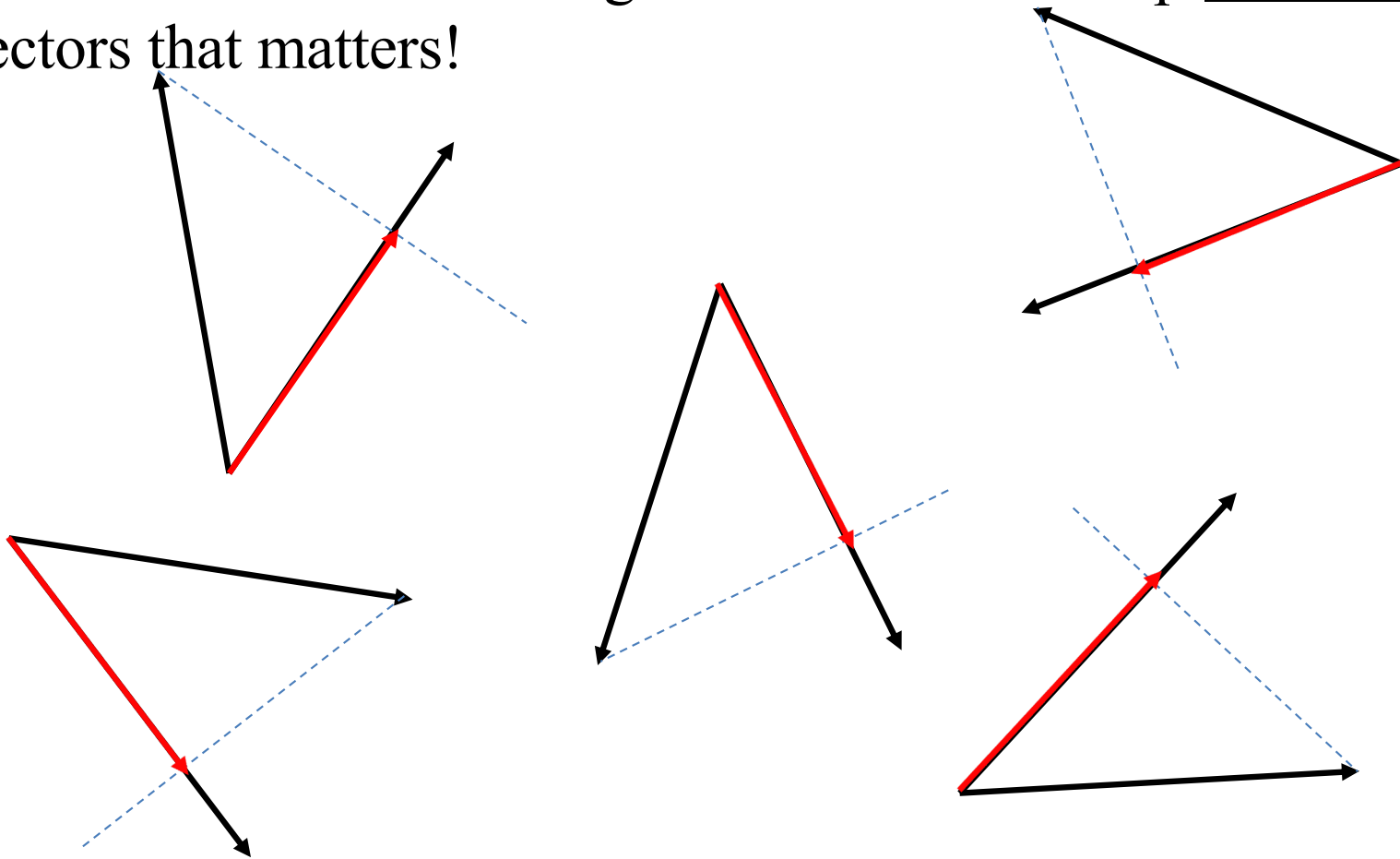
$$W = \vec{F} \cdot \vec{d}$$

*This is not* as spooky as it looks. It is just a mathematical operation. The point is that the *dot product* between a **force** and **displacement** tells you something about how that force is motivating the body to *change its motion*.



# Dot products

- Orientation means nothing - it's the relationship between the vectors that matters!



# Work as a scalar

- Work is a scalar, so it has no associated direction, as we saw in the previous slide. However, it can be positive or negative.
- Work only depends on force and displacement, and the angle between those vectors. Usually, this becomes  $W = Fd \cos \theta$ , where  $\theta$  is the angle between  $F$  and  $d$  (see triangle two slides back).
  - If  $F$  and  $d$  are parallel, what is  $\theta$ ?  
 $\theta = 0^\circ$  so  $\cos(0) = 1$ , and the entire force goes into doing work – the object's energy increases
  - If  $F$  and  $d$  are perpendicular, what is  $\theta$ ?  
 $\theta = 90^\circ$  so  $\cos(90) = 0$ , and that force does no work.  
*This is a major concept that you need to know!*
  - If  $F$  and  $d$  are in opposite directions, what is  $\theta$ ?  
 $\theta = 180^\circ$  so  $\cos(180) = -1$ , and that force does negative work – the object's energy decreases

# Work concept check

- In which case is work being done? Is that work + or -?
  - Carrying a bucket horizontally at constant velocity
    - No work – gravity and applied force are perpendicular to displacement (and velocity is unchanged)
  - Holding a heavy bag motionless while waiting for the bus
    - No work – bag is not displaced
  - Lifting a box from the ground to a table
    - Positive work is done by person as they lift upwards and the box displaces upwards
  - Pushing against a wall for an hour
    - No work – wall does not move. You might get really tired, but you do no work on the wall.

*How about a dot product* if the vectors are in **unit vector notation**? In that case:

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

which is to say, **the sum of the products of like component.**

*Justification:*

Let  $\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$  and  $\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$

$$\begin{aligned}\vec{A} \cdot \vec{B} &= (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) \\ &= A_x B_x \cos 0^\circ + A_x B_y \cos 90^\circ + \text{etc.}\end{aligned}$$

*Notice* the **like-terms stay** and the **off-terms go** away, so extrapolating:

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

*Example:* if  $\vec{A} = -3\hat{i} + 0\hat{j} + 5\hat{k}$  and  $\vec{B} = -2\hat{i} + 3\hat{j} - 5\hat{k}$

$$\begin{aligned}\vec{A} \cdot \vec{B} &= (-3)(-2) + (0)(3) + (5)(-5) \\ &= -19\end{aligned}$$